

QUIZ 1, SOLUTIONS.

1). a) V_1 is a vector space, since sums & scalar multiples of symmetric matrices are symmetric. |

V_2 is not a vector space since ~~$A \in V_2 \Rightarrow A \in V_2$~~ , |

$I \in V_2$ but $-I \notin V_2$. |

b). V_2 has dimension $1+2+3=6$, |

A basis for V_2 is given by the following collection of matrices.

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad 2$$

$$\begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}.$$

c). f_1 is a linear operator since $\text{trace}(A_1 + A_2) = \text{tr}(A_1) + \text{tr}(A_2)$.

& $\text{trace}(\alpha A_1) = \alpha \text{trace} A_1$. |

f_2 is not a linear operator since

~~det~~ $\det A_1 = 1$, $\det A_2 = -2$, but $\det(A_1 + A_2) = 0 \neq \det A_1 + \det A_2$

for $A_1 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$, $A_2 = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 2 \end{bmatrix}$. |

d). $L = f_1$. The range of L is \mathbb{R} . |

The kernel of L is the set of symmetric matrices having

zero trace. Since $\text{range } L = \mathbb{R}$, $\text{rank } L = 1$. |

$$\text{rank } L + \text{nullity } L = \dim V_1 = 6.$$

$$\text{Hence nullity } L = 6 - 1 = 5.$$

A basis for kernel L is given by

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix}, \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}.$$

$$2. \text{ Let } f_1(t) = e^t, f_2(t) = te^t, f_3(t) = t^2e^t.$$

$$\text{Suppose } \alpha_1 f_1 + \alpha_2 f_2 + \alpha_3 f_3 = 0.$$

$$\text{putting } t=0 \text{ yields } \alpha_1 = 0.$$

$$\therefore \alpha_2 te^t + \alpha_3 t^2e^t = 0 \quad \forall t \in (0, 1]$$

$$\Rightarrow \alpha_2 e^t + \alpha_3 te^t = 0 \quad \forall t \in (0, 1].$$

$$\text{Letting } t \rightarrow 0 \Rightarrow \alpha_2 = 0.$$

$$\therefore \alpha_3 = 0.$$

Thus f_1, f_2, f_3 are linearly independent

$$3. \text{ Let } u^1 = 1, u^2 = s, u^3 = s^2, u^4 = s^3.$$

$$L(u^1) = 2 = 2u^1$$

$$L(u^2) = 3 + 2s = 3u^1 + 2u^2$$

$$L(u^3) = 2 + 6s + 2s^2 = 2u^1 + 6u^2 + 2u^3$$

$$L(u^4) = \cancel{(12s)} + \cancel{3(6s^2)} + 2s^3 = 12u^2 + 18u^3 + 2u^4$$

The matrix representation of L in the basis $\{u^1, u^2, u^3, u^4\}$ is

$$\begin{bmatrix} 2 & 3 & 2 & 0 \\ 0 & 2 & 6 & 12 \\ 0 & 0 & 2 & 18 \\ 0 & 0 & 0 & 22 \end{bmatrix}.$$

The matrix representation has rank 4. $\therefore L$ has rank 4.
(OR) Note that the eqn. $L(p)=0$ has only exponential solutions,
 \therefore kernel $L \subseteq$ has no elements in $\mathbb{R}_3[s]$.

4 The set of invertible matrices do not form a field
because the sum of invertible matrices need not be invertible
eg. $I + -I$. 2.

Quiz 2, Solutions

1. $F(t) = \begin{bmatrix} e^t & e^{-t} \\ e^{-t} & e^t \end{bmatrix}$, $F(s) = \begin{bmatrix} e^s & e^{-s} \\ e^{-s} & e^s \end{bmatrix}$.

$$F(t) \cdot F(s) = \begin{bmatrix} e^{t+s} + e^{-(t+s)} & e^{t-s} + e^{s-t} \\ e^{s-t} + e^{t-s} & e^{-(t+s)} + e^{(t+s)} \end{bmatrix} \neq \dots$$

$$F(t+s) = \begin{bmatrix} e^{t+s} & e^{-(t+s)} \\ e^{-(t+s)} & e^{(t+s)} \end{bmatrix} \neq F(t) \cdot F(s).$$

$\therefore F$ is not a matrix exponential.

OR $F^{-1}(t) = \frac{1}{e^{2t} - e^{-2t}} \begin{bmatrix} e^t & -e^{-t} \\ -e^{-t} & e^t \end{bmatrix}$.

$$F(-t) = \begin{bmatrix} e^{-t} & e^t \\ e^t & e^{-t} \end{bmatrix} \neq F^{-1}(t).$$

2 Let $F(t) = e^{3t} \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$, $\dot{F}(t) = 3e^{3t} F(t)$.

$$AF(t) = e^{3t} \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} = e^{3t} \begin{bmatrix} 3 & 3 & 3 \\ 3 & 3 & 3 \\ 3 & 3 & 3 \end{bmatrix} = \dot{F}(t).$$

But $F(0) = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} \neq I$.

$\therefore F(t) \neq e^{At}$.

3

$$\dot{x}_1 = 2x_2, \dot{x}_2 = 2x_1 \Rightarrow \dot{x} = Ax, \text{ where}$$

$$A = \begin{bmatrix} 0 & 2 \\ 2 & 0 \end{bmatrix}. \quad A^2 = 4I \quad A^3 = 8A = 2P.$$

In general, ~~$A^{2k} = 2^{2k} I, A^{2k+1} = 2^{2k+1} A$~~

$$P^2 = I, P^3 = P, \dots \therefore P^{2k} = I, P^{2k+1} = P.$$

$$\therefore A^{2k} = 2^{2k} I, A^{2k+1} = 2^{2k+1} P.$$

$$\therefore e^{At} = I \left[1 + \frac{1}{2!} 2^2 t^2 + \frac{1}{4!} 2^4 t^4 - \dots \right]$$

$$+ P \left[2t + \frac{2^3 t^3}{3!} + \dots \right]$$

$$= I \left(\frac{e^{2t} + e^{-2t}}{2} \right) + P \left(\frac{e^{2t} - e^{-2t}}{2} \right)$$

$$= \begin{bmatrix} \frac{e^{2t} + e^{-2t}}{2} & \frac{e^{2t} - e^{-2t}}{2} \\ \frac{e^{2t} - e^{-2t}}{2} & \frac{e^{2t} + e^{-2t}}{2} \end{bmatrix}$$

IR $\phi_{x(0)} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$, then $x(t) = e^{At} \phi_{x(0)} = \frac{1}{2} \begin{bmatrix} e^{2t} + e^{-2t} \\ e^{2t} - e^{-2t} \end{bmatrix}$

4

$$A - 2I = \begin{bmatrix} -1 & 1 & 0 & 0 \\ -1 & 0 & 1 & 0 \\ -1 & 0 & 1 & 0 \\ -1 & 0 & 1 & 0 \end{bmatrix}$$

$$\text{rank}(A - 2I) = 2 < 4.$$

$\therefore 2$ is an eigenvalue.

Since nullity $(A - 2I) = 2$, geometric multiplicity = 2.

$$(A - 2I)^2 = \begin{bmatrix} 0 & -1 & 1 & 0 \\ 0 & -1 & 1 & 0 \\ 0 & -1 & 1 & 0 \\ 0 & -1 & 1 & 0 \end{bmatrix}$$

$$\text{rank}(A - 2I)^2 = 1.$$

$$\underline{\underline{4}} \quad (A-2I)^3 = 0.$$

~~S. that it is~~

∴ we conclude that algebraic multiplicity of $\lambda=2$ is 4.

∅

The Jordan block associated with $\lambda=2$ is

$$\left[\begin{array}{ccc|c} 2 & 1 & 0 & 0 \\ 0 & 2 & 1 & 0 \\ 0 & 0 & 2 & 0 \\ \hline 0 & 0 & 0 & 2 \end{array} \right]$$

$$\underline{\underline{S}}. \quad A^T A = \begin{bmatrix} 4 & 2 \\ 2 & 2 \end{bmatrix}$$

$$\det A^T A = 8 - 4 = 4 > 0.$$

∴ By Sylvester's criterion, $A^T A > 0$.

$$A + A^T = \begin{bmatrix} 0 & -1 \\ -1 & -2 \end{bmatrix}$$

$$A + A^T - \lambda I = \begin{bmatrix} -\lambda & -1 \\ -1 & -(\lambda+2) \end{bmatrix}$$

$$\det(A + A^T - \lambda I) = +\lambda(\lambda+2) - 1 = 0 \text{ i.e. } \lambda^2 + 2\lambda - 1 = 0.$$

$$\lambda = \frac{-2 \pm \sqrt{4+4}}{2} = -1 \pm \sqrt{2}. \Rightarrow A + A^T \text{ is indefinite}$$

$$A^T P_1 + P_1 A = \begin{bmatrix} 0 & 0 \\ 0 & -2 \end{bmatrix}$$

-ve semi definite.

$$A^T P_2 + P_2 A = - \begin{bmatrix} 4 & -1 \\ -1 & 4 \end{bmatrix}$$

$$\det \begin{bmatrix} 4 & -1 \\ -1 & 4 \end{bmatrix} > 0.$$

∴ $A^T P_2 + P_2 A$ is -ve definite.

3 (Alternative solution).

$$(sI - A) = \begin{bmatrix} s & -2 \\ -2 & s \end{bmatrix} \quad (sI - A)^{-1} = \begin{bmatrix} s & 2 \\ 2 & s \end{bmatrix} \frac{1}{s^2 - 4}$$

$$\frac{2}{s^2 - 4} = \frac{1}{2} \left[\frac{1}{s-2} - \frac{1}{s+2} \right] \quad \frac{s}{s^2 - 4} = \frac{1}{2} \left[\frac{1}{s+2} + \frac{1}{s-2} \right]$$

~~$$e^{At} = \mathcal{L}^{-1} \left[(sI - A)^{-1} \right]$$~~

$$\mathcal{L} e^{At} = \mathcal{L}^{-1} (sI - A)^{-1} = \begin{bmatrix} \frac{e^{-2t} + e^{2t}}{2} & \frac{e^{2t} - e^{-2t}}{2} \\ \frac{e^{2t} - e^{-2t}}{2} & \frac{e^{-2t} + e^{2t}}{2} \end{bmatrix}$$

$$x(0) = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \Rightarrow x(t) = e^{At} x(0) = \frac{1}{2} \begin{bmatrix} e^{2t} + e^{-2t} \\ e^{2t} - e^{-2t} \end{bmatrix}$$

Quiz 3, Solutions

1. $P(t) = \int_0^t e^{A\tau} B B^T e^{A^T \tau} d\tau$. Clearly, $P(0) = 0$.

$$\dot{P}(t) = e^{At} B B^T e^{A^T t}$$

$$AP + PA^T + BB^T = \int_0^t [A e^{A\tau} B B^T e^{A^T \tau} + e^{A\tau} B B^T e^{A^T \tau} A^T] d\tau + BB^T$$

$$= \int_0^t \frac{d}{d\tau} (e^{A\tau} B B^T e^{A^T \tau}) d\tau + BB^T$$

$$= e^{At} B B^T e^{A^T t} - BB^T + BB^T = \dot{P}(t)$$

Thus $\dot{P} = AP + PA + BB^T$ & $P(0) = 0$.

2. Suppose $A^T P + PA + 2\mu P = -\alpha$, $P > 0$, $\alpha > 0$, $\mu > 0$.

Let $\lambda \in \mathbb{C}$ be an eigenvalue of A with eigenvector $v \in \mathbb{C}^n$. Then $Av = \lambda v$ & $v^* A^T = \bar{\lambda} v^*$.

$$\begin{aligned} \therefore v^* (A^T P + PA + 2\mu P) v &= \bar{\lambda} v^* P v + \lambda v^* P v + 2\mu v^* P v \\ &= -v^* \alpha v \end{aligned}$$

$$\therefore (\lambda + \bar{\lambda}) v^* P v = -2\mu v^* P v - v^* \alpha v$$

Since $v^* P v > 0$ & $v^* \alpha v > 0$, we conclude that

$$2 \operatorname{Re} \lambda = \lambda + \bar{\lambda} < -2\mu.$$

$$\therefore \operatorname{Re} \lambda < -\mu.$$

Since λ was chosen arbitrarily, the conclusion follows.

3. The controllability matrix is

$$C = \begin{bmatrix} 1 & 2 & +4 \\ 0 & 5 & -5 \\ 0 & -5 & 5 \end{bmatrix} \quad \text{which has rank 2.}$$

The system is not controllable.

$$\text{range } C = \text{span} \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix} \right\}.$$

Since $x_f = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \notin \text{range } C$, it follows that there

exists no input that steers $x_i = 0$ to x_f .

The observability matrix is

$$O = \begin{bmatrix} 1 & 1 & 2 \\ -3 & 2 & -1 \\ 9 & 4 & 13 \end{bmatrix}$$

If x_1 & x_2 have to yield the same outputs, then

$$C e^{At} (x_1 - x_2) = 0, \quad \text{i.e. } x_1 - x_2 \in \text{kernel } C.$$

$$x_1 - x_2 = \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix} \quad \& \quad O(x_1 - x_2) = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}.$$

∴ Outputs generated by x_1 & x_2 are the same.

4. $(A - 2I) = \begin{bmatrix} 0 & 1 & 1 \\ 5 & 1 & 6 \\ -5 & -1 & -6 \end{bmatrix}$ which has rank 2.

$\therefore 2$ is an eigenvalue of A .

The only left eigenvector is $v = \begin{bmatrix} \cancel{0} & \cancel{1} & \cancel{1} \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}^T$

$vB = 0$ \therefore eigenvalue 2 is not controllable.

$(A + 3I) = \begin{bmatrix} 5 & 1 & 1 \\ 5 & \cancel{6} & 6 \\ -5 & -1 & -1 \end{bmatrix}$ which has rank 2.

$\therefore -3$ is an eigenvalue.

The right eigenvector of -3 is $v = \begin{bmatrix} \cancel{1} \\ \cancel{0} \\ \cancel{1} \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix}$

$Cv = -1 \neq 0$.

$\therefore -3$ is observable.