

An Introduction to Simulated Annealing

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PRESENTATION OUTLINE

- (HISTORICAL BACKGROUND
- (GLOBAL OPTIMIZATION OF MULTI-MODAL FUNCTIONS
- (*MARBLE IN CUBE* ANALOGY
- (S A ALGORITHM
- (FEATURES OF S A
- (TUNING OF S A PARAMETERS
- (S A V/S CONVENTIONAL METHODS
- (S A FOR FUNCTIONS OF CONTINUOUS VARIABLES
- (APPLICATIONS OF S A
- (IMPROVEMENTS TO THE BASIC ALGORITHM
- (*SIMANN* S A ALGORITHM

GLOBAL OPTIMIZATION OF MULTI-MODAL FUNCTIONS

(How to reach **F**, starting from any **x** ?

u Greedy Algorithms ==> nearest local minimum

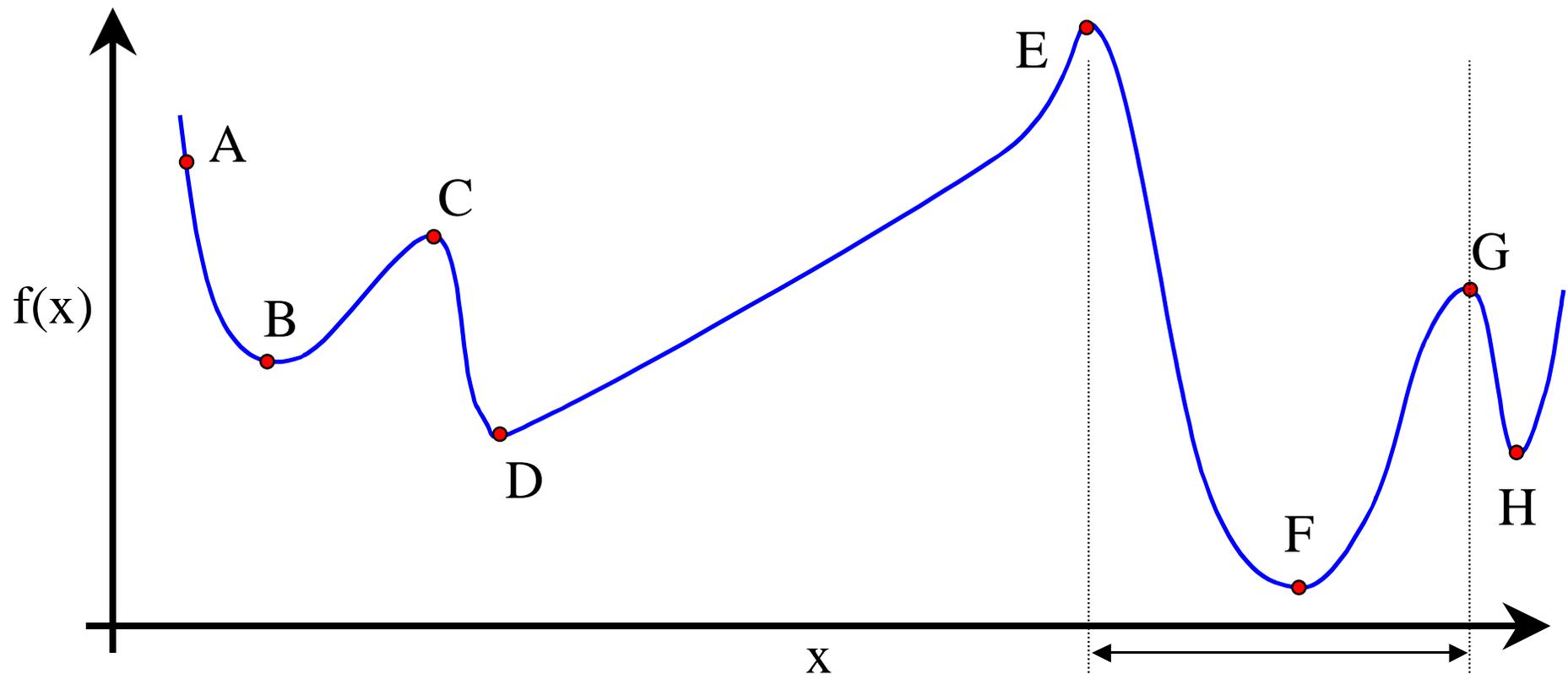
s A ==> B

C ==> D

E ==> F

G ==> H

s multiple starts from various initial **x** values



NON-GREEDY ALGORITHMS

- (Permit occasional uphill moves
 - u sparingly, and in a controlled manner
- (Large uphill moves
 - u In the initial stages
 - better domain exploration
 - u Large changes in $f(\mathbf{x})$
 - better chance of improvement
 - u Once in a while
 - to climb out of local minima

HISTORICAL BACKGROUND

(Numerical simulation of Annealing Metropolis et. al, 1953

$$p(dE) = e^{(-dE/kT)}$$

T = *temperature*

$p(dE)$ = *probability of an increase in energy by dE*

k = *Boltzmann's constant*

(Combinatorial Optimization Kirkpatrick et. al, 1980

Cerny, 1985

Thermodynamic Simulation

System States

Energy

Change of state

Temperature

Frozen state

Combinatorial optimization

Feasible solutions

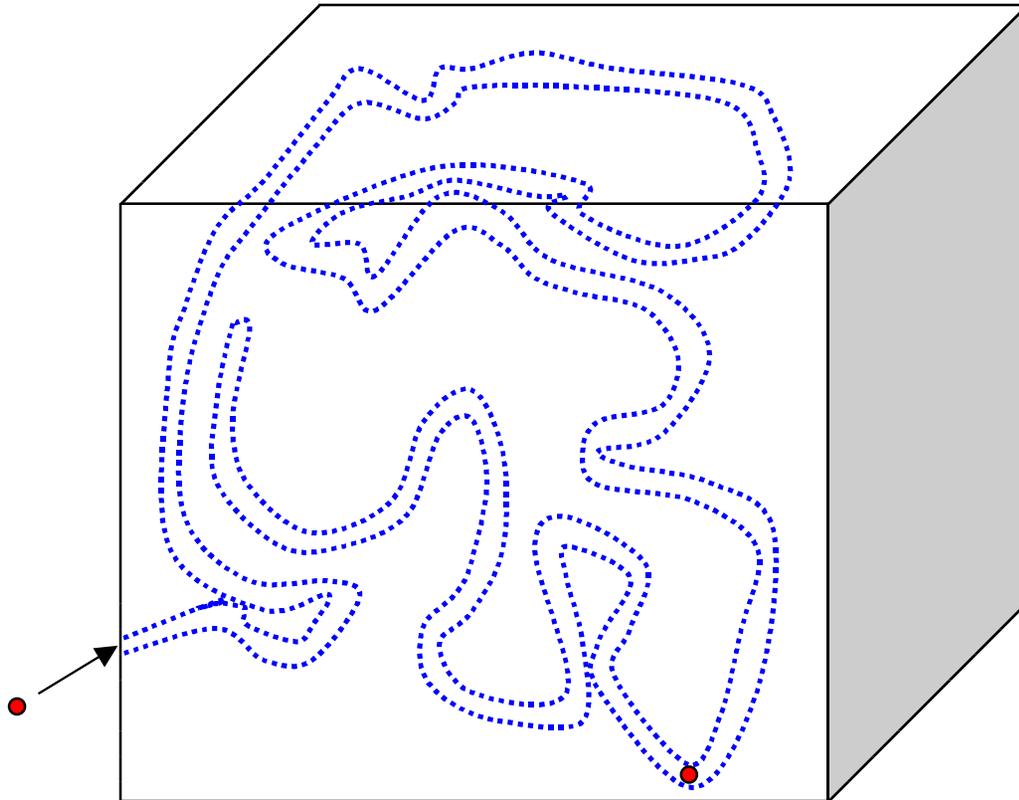
Cost

Neighboring solution

Control Parameter

Heuristic Solution

MARBLE-IN-CUBE ANALOGY



How to take the marble to the lowest position in the cube ?

SA ALGORITHM

Solution space X

Objective function f

Neighborhood structure N

Select Initial point s_0

Select Initial temperature $T_0 > 0$

Select temperature reduction function a

Repeat

Repeat

Randomly select $s \in N(s_0)$

$\Delta f = f(s) - f(s_0)$

If $\Delta f < 0$

then $s_0 = s$

else

generate a random number $r \in (0,1)$

if $r < e^{(-\Delta f / T_0)}$ then $s_0 = s$

Until iteration_count = max. iteration

Set $T = a(T)$

Until stopping condition = TRUE

s_0 is the approximation to the global minimum solution

FEATURES OF SA

- (Direct Method & Non-Greedy algorithm
 - u Global optimization of multi-modal, discontinuous & noisy functions
- (Mathematically proven to converge to global optimum
- (Very simple architecture

- (Parameters to be decided
 - u Solution space X , Objective function f
 - s user defined
 - u Neighborhood structure N
 - s should be adaptively modified
 - u Initial point s_0
 - s can be randomly selected
 - u Initial temperature T_0 & Temperature reduction function a
 - s ensure proper “annealing”
 - u Stopping Criteria
 - s max. number of function evaluations
 - s minimum improvement in f acceptable

SA V/S CONVENTIONAL METHODS

- (Very large number of function evaluations
 - u nearly 1000 times more !
 - u Exact optimal solution not reached in finite time
- (Tuning of SA parameters required before starting
 - u may take up 50% of the total time !
- (Cannot implicitly handle constraints
 - u Penalty Function approach

Example of Penalty Function

$$\text{Objective Function} = F_{\text{objt}} + \sum P_k$$

$$P_k = \sum_{k=1}^s i v_k i a c t_k w_k \text{constr}_k$$

s k = number of constraints

s constr_k = numerical value of k^{th} constraint

s $i v_k$ = 1 if $\text{constr}_k > \text{tol}_k$, = 0 otherwise

s tol_k = tolerance on target value for k^{th} constraint

s $i a c t_k$ = 1 if k^{th} constraint is active, = 0 otherwise

s w_k = weight on the value of k^{th} constraint

APPLICATIONS OF SA

(Combinatorial problems

- u VLSI & Computer system design
 - s optimal placement of $> 10^6$ transistors on a chip
 - s optimal location of services on a computer network
- u Sequencing & production scheduling
 - s Shop-floor, inventory management, FMS
- u Transport Scheduling & Time-tabling
 - s Travelling Salesman problem, Locomotive Scheduling
 - s Image processing, Building layout design, DNA mapping

(Continuous and mixed functions

- u Engineering Design
 - s Aircraft Conceptual Design, Composite Structure modelling
- u Statistical Functions
 - s Banking industry, and Financial analysis

SA FOR CONTINUOUS VARIABLES

(Corana et. al

- u ACM transactions on Mathematical Software, **13**(3), 1987

(Features

- u Iterative random search procedure, with adaptive step size reduction
- u maintaining approx. 1:1 rate between accepted and rejected moves

(Tests

- u against Nelder-Mead simplex & Adapted Random Search, on
 - s 2 & 4 dim. Rosenbrock's valley function
 - always reached the global minimum
 - 500 to 1000 times higher n_{eval} , compared to Nelder-Mead Simplex
 - s parabolic, multi-minima discontinuous function
 - sometime converged to near-global optimal solutions
 - 20% lower total n_{eval} compared to other methods

(Pending tasks

- u How to decide T_{int} , better stopping criteria, and SA parameters ??

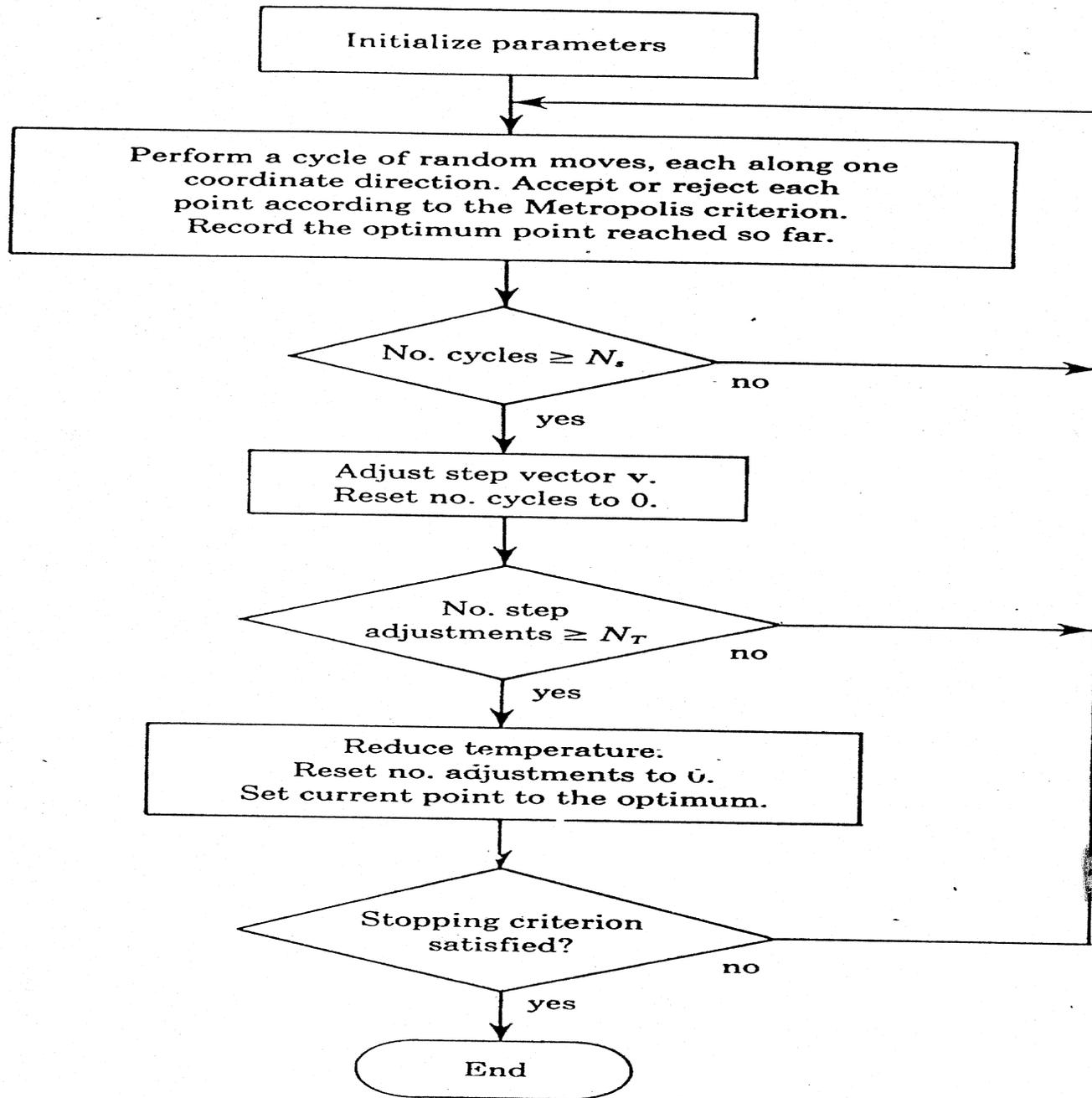
TUNING OF SA PARAMETERS

- u Initial Annealing Temperature (T_{int})
 - s of the order of expected objective function value
- u Temperature reduction factor (R_T)
 - s 0.85
- u No. of cycles before Temperature reduction (N_T)
 - s $\max(100, 5*n)$
- u Initial step sizes for design variables (v_i)
 - s does not matter, as it is changed adaptively
- u No. of cycles before step reduction (N_S)
 - s 20
- u No. of cycles for checking convergence (N_{eps})
 - s 4
- u Minimum reduction in Obj. Fun. before termination (eps)
 - s user defined

SIMANN SA CODE

- (Developed by William Goffe, Univ. of S. Mississippi, 1990
 - u Journal of Econometrics, **60**, pp. 65-99, 1994
 - u based on algorithm by Corana et. al
- (FORTRAN source code available from author / Internet
- (Quandt's GQOPT6 Statistical Optimization Package
- (Well tested for several statistical objective functions
 - s 4 econometric problems & 3 optimization methods from IMSL library
 - s best solution in each case with SIMANN
 - s independent of starting values
- (Improvements
 - u test for *globalness* of solution
 - u restriction of the search area to parameter subspace
 - u methodology for tuning of SA parameters

SIMANN FLOW CHART



The SA minimization algorithm.

TUNING OF SIMANN PARAMETERS

- (Determination of T_{int}
 - u Trial run with $T_{int} = 1$ and $R_T = 1.5$
 - s Determine T^* at which v_i cover design variable range
 - u Trial run with very high T_{int}
 - s Determine T^* at which v_i decrease rapidly
 - u Set T_{int} slightly greater than T^*
- (Determination of R_T & N_T
 - u low value => Quenching
 - u High value => increase in N_{eval}
 - u Few trial runs with progressively decreasing R_T & N_T values
 - u Assign highest values without loss in quality of the solution

TUNING OF SIMANN PARAMETERS

- u Selection of v_i
 - s 50% of the range of each design variable
 - s Not very important, as it is adjusted automatically
- u Selection of N_s
 - s Problem dependent, and determined by trial-and-error
- u Selection of N_{eps}
 - s Large value (4 or 5) for multi-minima functions
- u Selection of eps
 - s Problem dependent
 - s Accuracy of objective function calculation
 - s perception of what constitutes worthwhile improvement

SPECIAL FEATURES OF *SIMANN*

- (Robust and easy to use algorithm
 - u fully self-contained, including random number generator
 - u easy to use input file structure, and fairly detailed output file

- (Final step sizes indicate sensitivity of design variables

- (Excellent tutorial, with Judge's 2 variable test function

- (Number of function evaluations almost constant

The End